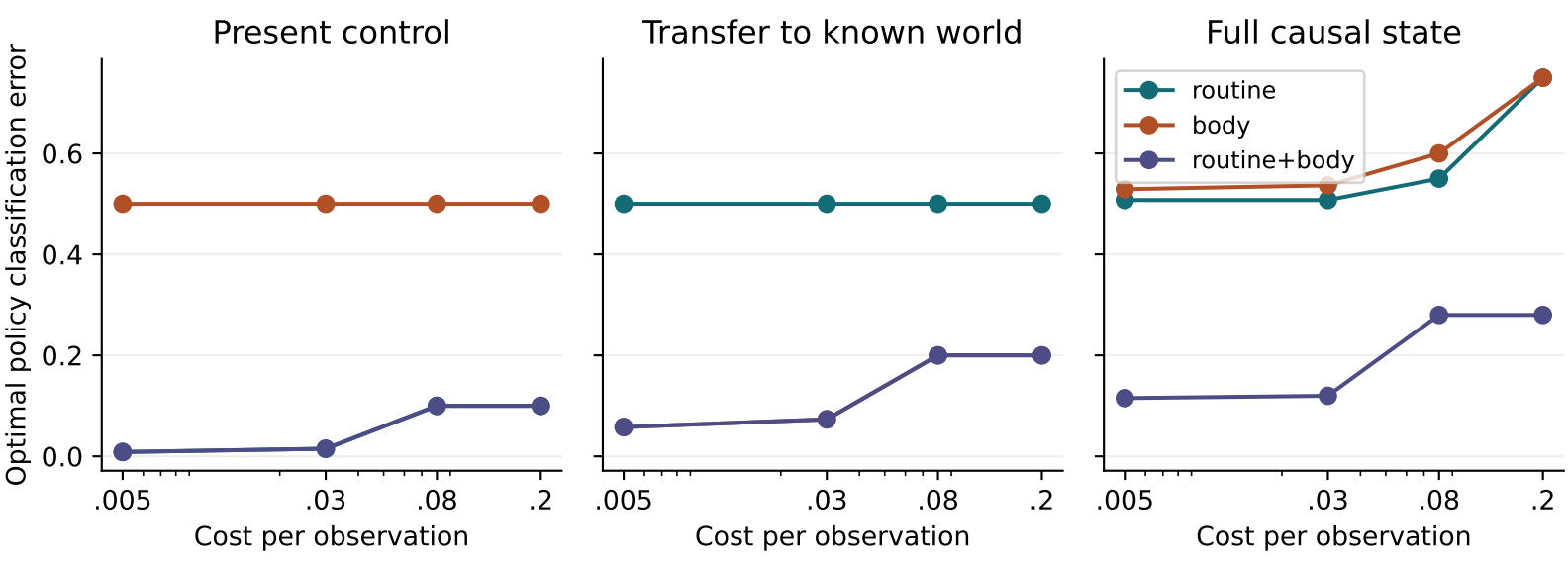

Present control
Transfer to known world
Full causal state
Optimal policy classification error
0.0
0.2
0.4
0.6
.005
.03
.08
.2
Cost per observation
routine
body
routine+body